

Data Reconstruction Attacks and Defenses: From Theory to Practice

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<https://arxiv.org/abs/2212.03714>

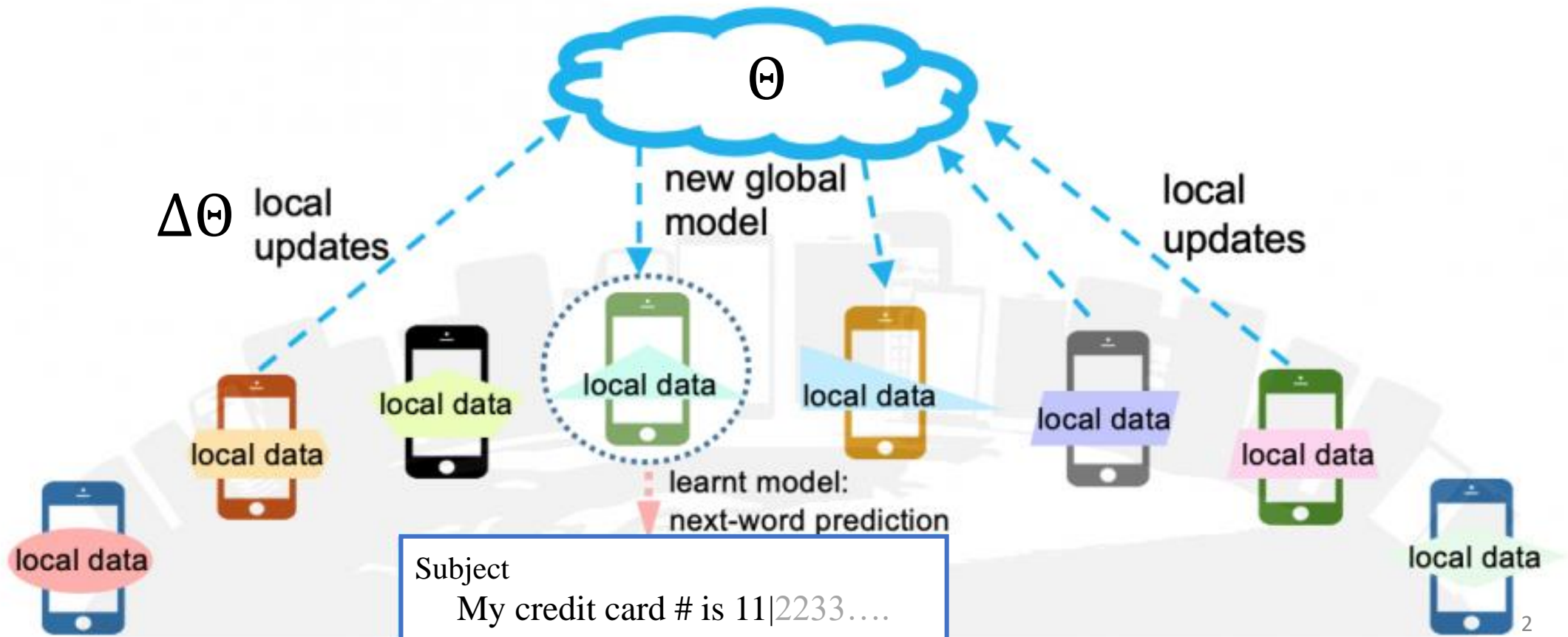
<https://arxiv.org/abs/2402.09478>

<https://arxiv.org/abs/2312.05720>

Federated learning

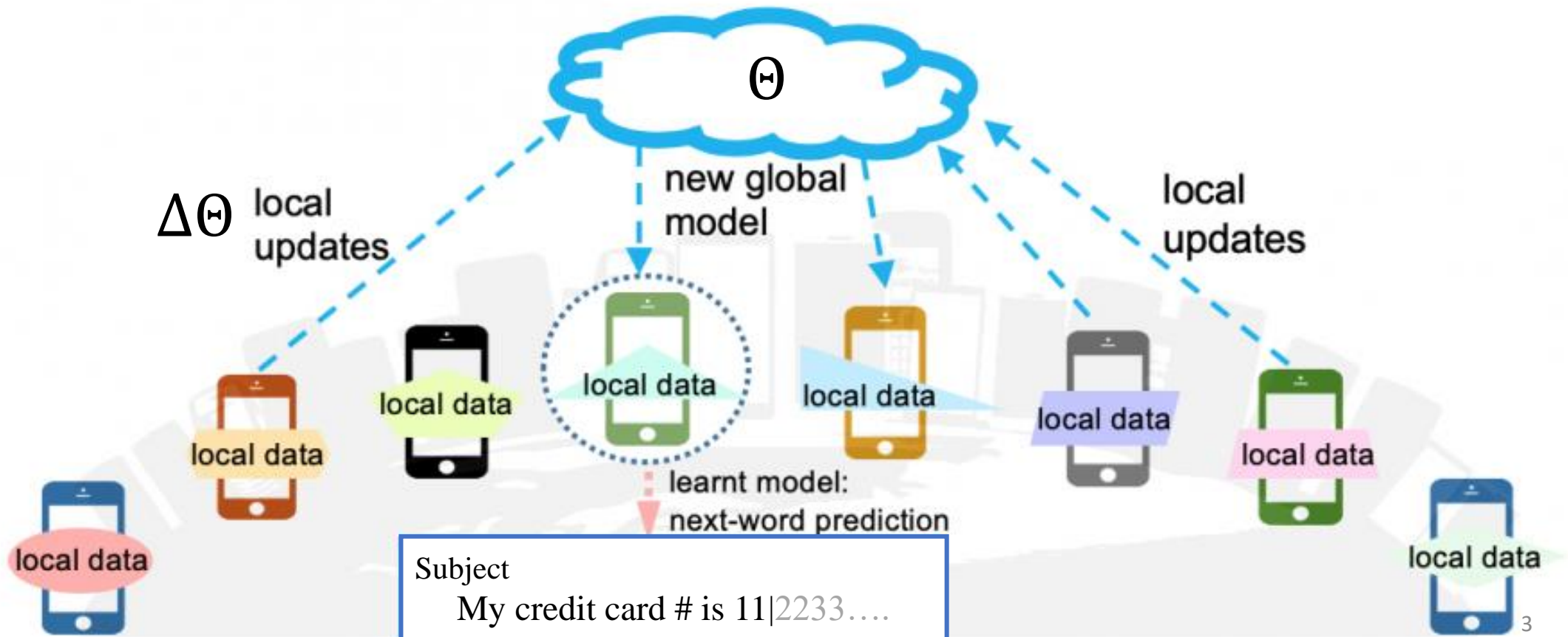
[Konečný et al. 2016, McMahan et al. 2017]

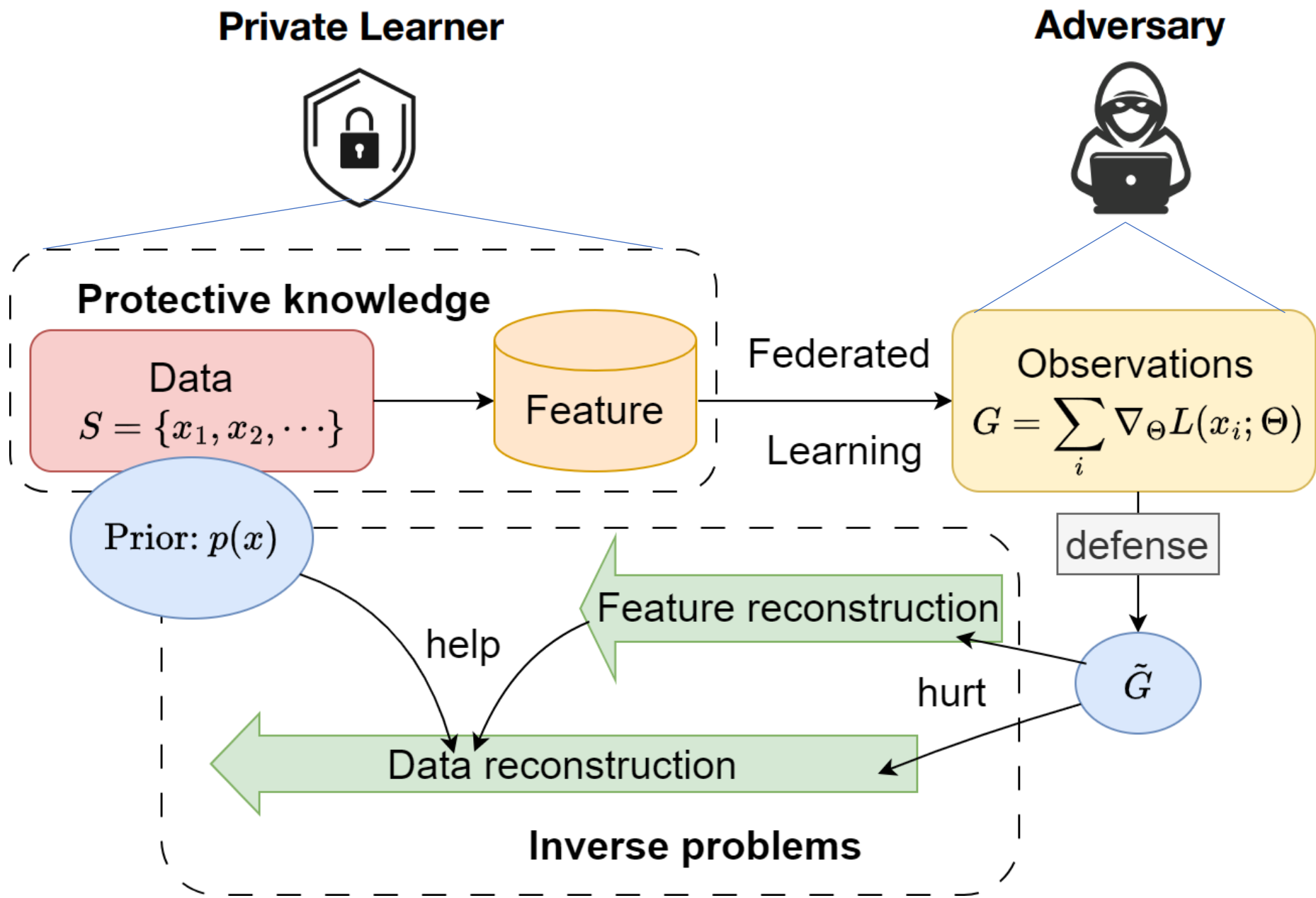
- Privacy leakage in distributed learning - Data and model not co-located



Privacy leakage in distributed learning

- Does local update reveal the training data?





Threat model more formally:

- Local batch of data:
 - $S = \{(x_1, y_1), (x_2, y_2), \dots, (x_B, y_B)\}$
 - Prediction function:
 - $x \rightarrow f(x; \Theta)$
 - Local update:
 - $G := \frac{1}{B} \nabla_{\Theta} \sum_{i=1}^B \ell(f(x_i, \Theta), y_i)$
 - Inverse problem:
 - Recover S from G , Θ is known
- Adversary {
- } Private learner

Fundamental questions

- When is the model gradient G sufficient to identify the training samples?
- If so, is there an efficient algorithm to recover the samples?

Fundamental questions

- When is the model gradient G sufficient to identify the training samples?
 - defending with information-theoretic bottleneck guarantees
- If so, is there an efficient algorithm to recover the samples?
 - defending with computational barriers

Prior work

- Attacking methods

- Learn to generate the training samples from a local user

- Match the gradient: $\min_{S=\{(x_i, y_i)\}} \left\| G - \sum_{i=1}^B \nabla \ell(f(x_i; \Theta), y_i) \right\|^2$

- Defending methods

- Quantizing/pruning the gradient
- Dropout
- Secure aggregation
- Multiple local aggregation
- Add noise

[Zhu et al., 2019; Yin et al., 2021; Jeon et al., 2021]

Prior work

- Theoretical analysis
 - Differential Privacy: more tailored for membership inference attack
 - Renyi-DP: reconstructing last sample with other samples known

Illustrating example:

- $S = \{x_1, x_2, \dots, x_B\}$, $G = x_1 + x_2 + \dots + x_B$
- No DP guarantee, not possible to reconstruct (unless with prior information)

Prior work

- Theoretical analysis
 - Differential Privacy: more tailored for membership inference attack
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- A more common trajectory in security:
 - ➔ stronger attack ➔ stronger defense ➔ ...

Warm-up:

- Two-layer neural network

$$f(x; \{W, a\}) = \sum_{j=1}^m a_j \sigma(w_j^\top x) = a^\top \sigma(W^\top x)$$

- Choose proper $\Theta = \{w_j, a_j\}$ to query the gradient at

$$\nabla_{a_j} L = \sum_{i=1}^B l'_i \sigma(w_j^\top x_i)$$

Our findings: recover third moment of data

- We want to estimate $T_p := \sum_{i=1}^B E_w [\sigma^{(p)}(w^\top x_i)] x_i^{\otimes p}$
- Uniquely identify $\{x_1, x_2, \dots, x_B\}$ through tensor decomposition when data is linearly independent for $p \geq 3$. [Kuleshov et al. 2015]
- Our strategy: choose $a_j = \frac{1}{m}$, $w_j \sim N(0, I)$, estimate T by
$$\widehat{T}_3 := \frac{1}{m} \sum_{j=1}^m g(w_j) H_3(w_j), \quad g(w_j) := \nabla_{a_j} L$$

Tensor decomposition

- Stein's lemma: $E_{w \sim N(\mathbb{0}, I)} [g(a^\top w) H_p(w)] = E[g^{(p)} a^{\otimes p}]$.
- Hermite function: $H_2(w) = ww^\top - I, H_3(w) = w^{\otimes 3} - w \widetilde{\otimes} I$.
- $\widehat{T}_p := \frac{1}{m} \sum_{j=1}^m g(w_j) H_p(w_j) \approx E_{w \sim N(\mathbb{0}, I)} [g(w) H_p(w)]$
 $\equiv \sum_{i=1}^B E \left[\sigma^{(p)}(w^\top x_i) x_i^{\otimes p} \right] =: T_p$
- $g(w_j) := \nabla_{a_j} L = \sum_{i=1}^B l'_i \sigma(w_j^\top x_i)$ is our observation from the model gradient

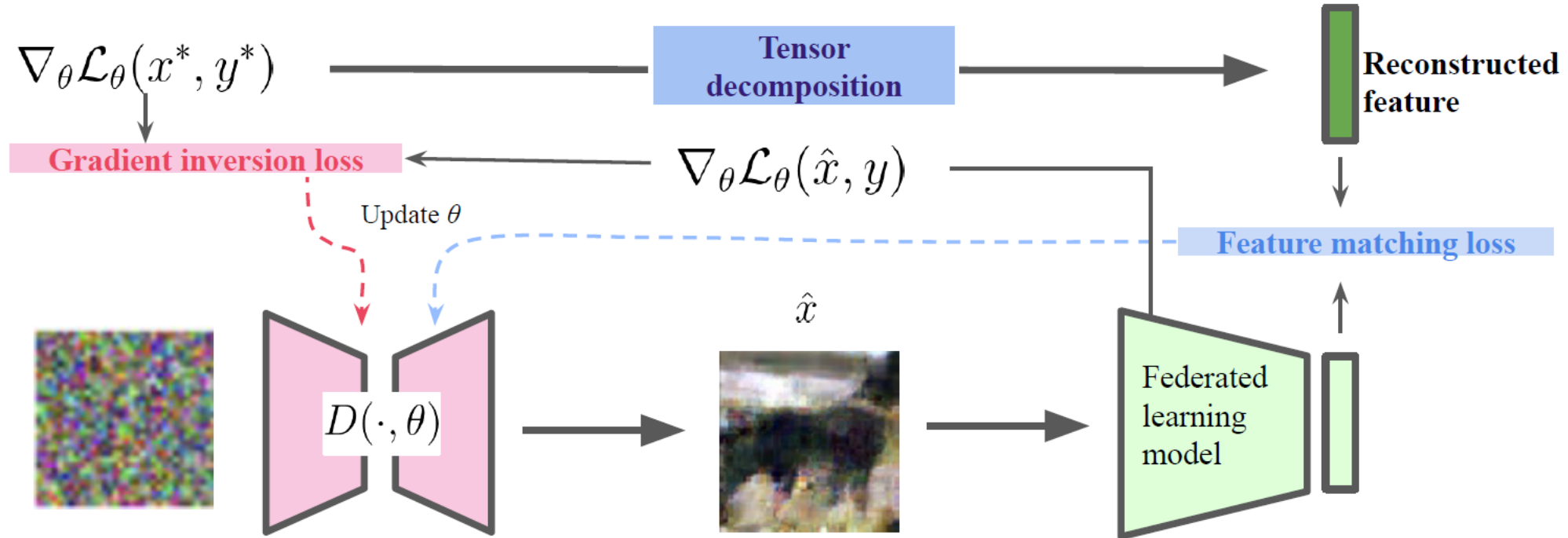
Theoretical analysis on attack

- Applies when $E[\sigma^{(3)}(w)]$ or $E[\sigma^{(4)}(w)] \neq 0$. Applies to sigmoid, tanh, ReLU, leaky ReLU, GeLU, SELU, ELU etc.
- Reconstruction error $\leq \tilde{O}(\sqrt{d/m})$.

Theoretical analysis on defense

- No defense: error $\leq \tilde{O}\left(\sqrt{d/m}\right)$
- K-Local aggregation: error $\leq \tilde{O}\left(K\sqrt{d/m}\right)$
- Add σ^2 -noise: error $\leq \tilde{O}\left(\sqrt{(1 + \sigma^2)d/m}\right)$
- K-Secure aggregation: error $\leq \tilde{O}\left(K\sqrt{d/m}\right)$
- p-Dropout: error $\leq \tilde{O}\left(\sqrt{d/pm}\right)$
- Gradient pruning: not applicable

Beyond two-layer networks



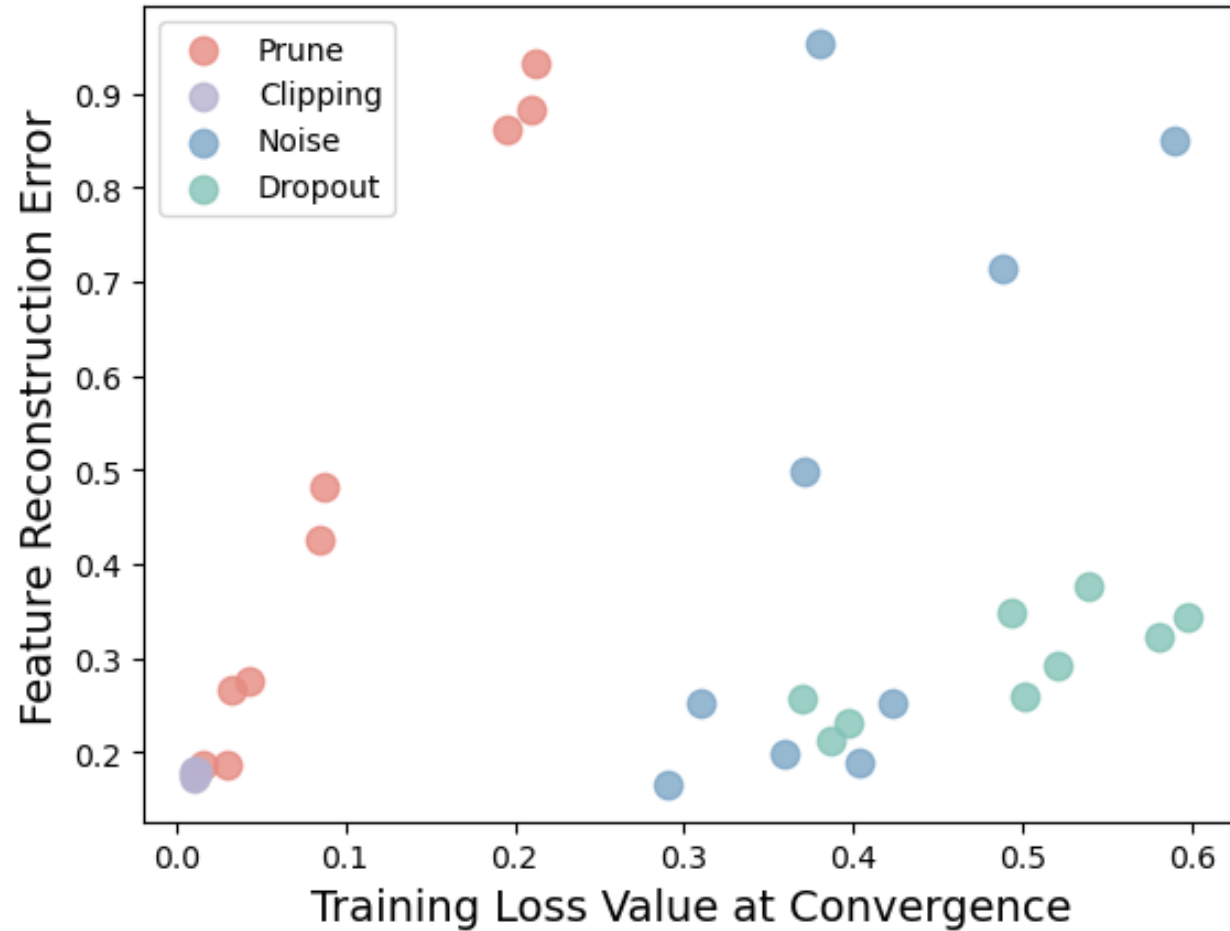
- Previous findings: if last two layers are fully connected, can recover the features from the $(l - 2)$ -th layer
- Other structured data modalities: recover the embeddings first

Empirical results:



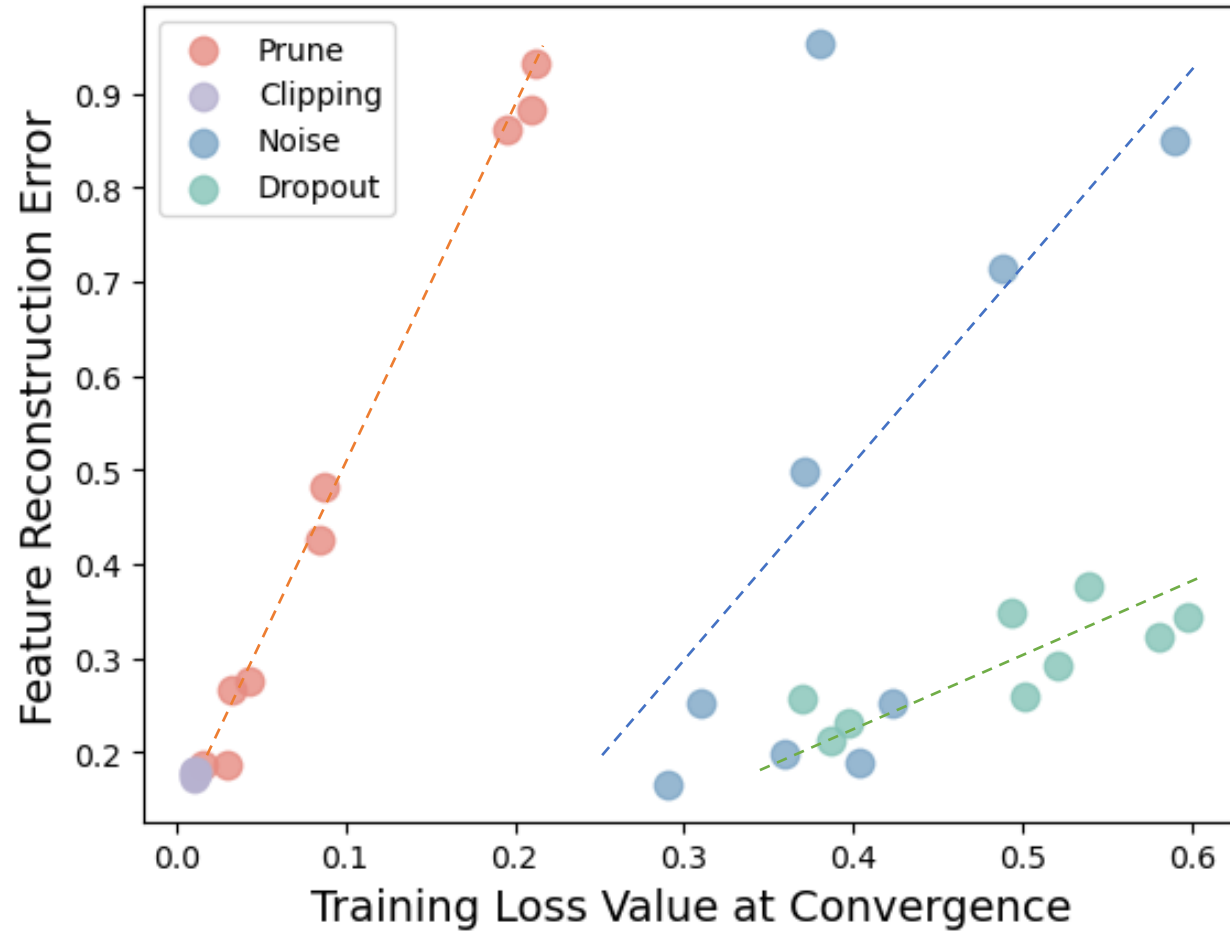
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Privacy-utility trade-offs



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Privacy-utility trade-offs



Beyond computer vision tasks...

Dataset	Method	R-1	R-2	R-L	Cos _S	Recovered Samples
CoLA	reference sample: The box contains the ball					
	LAMP	15.5	2.6	14.4	0.36	likeTHETw box contains divPORA
	Ours	17.4	3.8	15.9	0.41	like Mess box contains contains balls
SST2	reference sample: slightly disappointed					
	LAMP	20.1	2.2	15.9	0.56	likeslightly disappointed a
	Ours	19.7	2.1	16.8	0.59	like lightly disappointed a
Toma	reference sample: vaguely interesting, but it's just too too much					
	LAMP	19.9	1.6	15.1	0.48	vagueLY', interestingtooMuchbuttoojusta
	Ours	21.5	1.8	16.0	0.51	vagueLY, interestingBut seemsMuch Toolaugh

More results in: [Li et al. 2024] <https://arxiv.org/abs/2312.05720>

Discussions

- Gradient pruning is the most effective defending method (theoretically, empirically: better privacy-utility trade-off)
- Call for more tailored concept of privacy in reconstruction attack in federated learning
- Information-theoretical or computational lower bound in reconstruction attack

Thank you